Huma20 O4 Pro

Sub250 · 2" FPV cinewhoop with DJI O4 Air Unit Pro
User Manual · 4S ELRS version



Read the entire manual before your first flight, in particular the safety instructions (chapter 1) and the legal requirements for operation (chapter 3).

Importer: Rotorama, s.r.o. · www.rotorama.com

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1. Safety instructions

1.1 Before you start

The Sub250 Huma20 O4 Pro is a high-performance cinewhoop-class FPV drone powered by a 4S Li-Po battery. It is not a toy and is not intended for children. Improper handling may cause personal injury, property damage or fire. Read the entire manual before your first flight.

- The drone may only be flown by a person who meets the requirements applicable in the country of operation (age, operator registration, pilot competency) – see chapter 3.
- Carry out a pre-flight check before every flight (chapter 6.1). Never use a damaged drone.
- Do not fly under the influence of alcohol, drugs or medication that impairs alertness, or when tired.
- Do not tamper with the drone's electronics unless you are sure of what you are doing. Any modifications to the hardware or firmware are made at your own risk.

1.2 Rotating propellers and mechanical hazards

- The motors spin at high speed. The propeller guard (duct) reduces the risk but **does not eliminate injury** from a rotating propeller.
- Whenever you work on the drone (assembly, configuration, connecting to a computer), **disconnect the battery**. Always remove the propellers when testing the motors in Betaflight Configurator.
- Before connecting the battery, switch Arm (motor enable) off on the radio and set the throttle to minimum.
- Keep a safe distance from people and animals. After landing, do not pick up the drone until it is in the Disarm state (motors disabled).
- The DJI O4 Air Unit Pro camera and video transmitter become very hot during operation. Do not touch them until they have cooled down.

1.3 Li-Po and LiHV batteries

- Charge batteries only with a suitable Li-Po / LiHV charger, on a non-flammable surface and under supervision. Never charge them while installed in the drone.
- Do not use swollen, punctured, deformed or otherwise damaged batteries. Take a damaged battery out of service immediately.
- Do not short-circuit the battery or expose it to temperatures above 60 °C, direct sunlight or moisture. Do not throw it into fire.
- Fully charged battery: 4.20 V/cell (Li-Po) or 4.35 V/cell (LiHV). End the flight at 3.5 V/cell at the latest. For storage, set 3.8 V/cell.
- After a flight, let the battery cool down before recharging it.

- Transport and store batteries in a fireproof container (Li-Po bag).

1.4 Operating environment

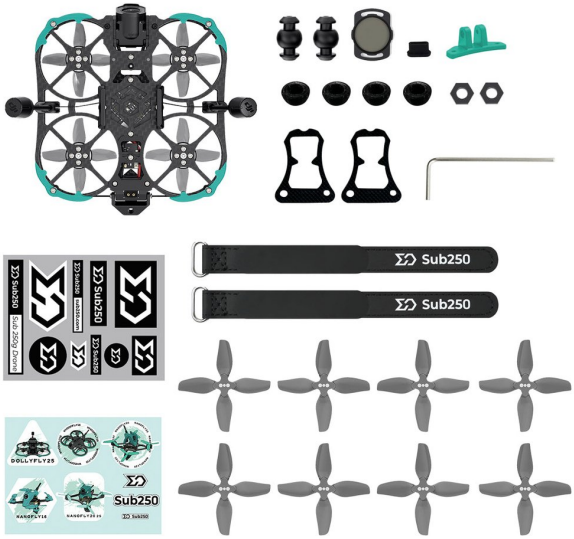
- Do not fly in rain, snow, fog, strong wind or reduced visibility. The drone's electronics are not waterproof.
- According to the manufacturer DJI, the operating temperature of the DJI O4 Air Unit Pro video transmitter is −10 °C to 40 °C.
- Do not fly near high-voltage power lines, transmitter masts or airports, or in restricted zones.
- The video transmitter relies on airflow for cooling. If the powered-on drone stands on the ground for a longer time, it overheats – according to DJI, it switches to a power-saving mode after power-on, and when overheated it stops recording and reduces transmission quality. Therefore, take off without unnecessary delay after connecting the battery.

2. Product description

2.1 Package contents

The manufacturer shows the package contents only in a picture (without labels). According to it, the package contains:

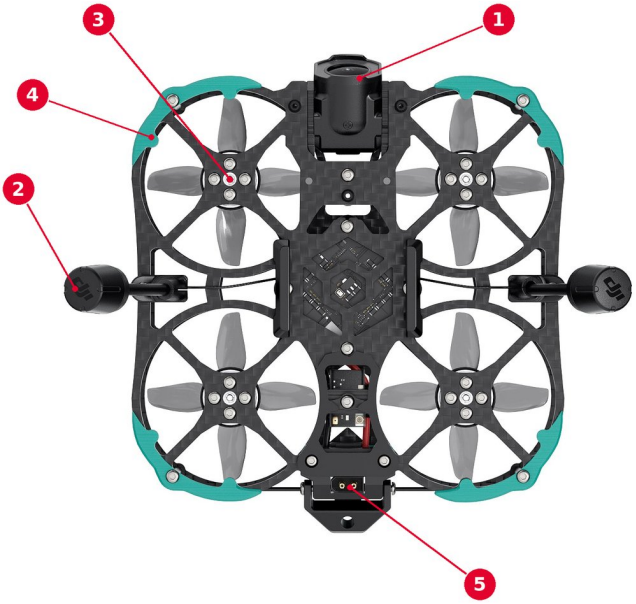
- Huma20 O4 Pro drone with built-in DJI O4 Air Unit Pro video transmitter and ExpressLRS 2.4 GHz receiver,
- spare HQProp 2×2.2×4 propellers (8 pcs in the picture),
- 2 battery straps,
- hex key,
- a set of small mounting parts (dampers, nuts, carbon washers, plastic mount, cover and more),
- sticker sheets.



Package contents as shown in the manufacturer's picture (for illustration)

※ The battery, charger, radio (RC transmitter) and FPV goggles are not included.

2.2 Parts description



View of the drone, front at the top

① DJI O4 Air Unit Pro camera on a damped mount
② DJI O4 Air Unit Pro video transmitter antennas (2 pcs)
③ Sub250 1304 6000 KV motor with HQProp 2×2.2×4 propeller (4×)
④ Propeller guard (duct)
⑤ XT30 power connector for the battery

2.3 Specifications

Parameter	Value
Model	Sub250 Huma20 O4 Pro, 4S ELRS version
Manufacturer	Sub250, www.sub250.com, support@sub250.com
Type	2" cinewhoop with propeller guards
Wheelbase (diagonal motor-to-motor distance)	95 mm
Carbon plate thickness	2 mm
Weight without battery	142 ± 1 g
Motors	Sub250 1304, 6000 KV
Propellers	HQProp 2×2.2×4
Flight controller + ESC (AIO)	Sub250 Redfox A3 45A AIO
Processor (MCU)	STM32F722RET6
Gyroscope	ICM42688-P
ESCs	BLHeli_32, 45 A
Receiver	ExpressLRS 2.4 GHz
Video transmitter / camera	DJI O4 Air Unit Pro
Video transmitter mounting pattern	20 × 20 mm / 25.5 × 25.5 mm
Battery	4S Li-Po; 720 mAh recommended by the manufacturer
Power connector	XT30

Source: Sub250 manufacturer specifications on the product page.

2.4 Flight controller (FC) and receiver

The drone uses the **Redfox A3 45A AIO** board, which combines the flight controller (FC) and a 4-in-1 ESC on a single board. Data according to the manufacturer's manual for the Redfox A3 board:

Parameter	Value
Flight controller firmware	Betaflight, target **SUB250REDFOXF722AIO**
ESC firmware	BLHeli_32
ESC protocol	DShot300, DShot600
ESC continuous / burst current	45 A / 55 A (10 s)
BEC output	5 V / 2.5 A
USB	SH1.0 5-pin, USB-C adapter

Parameter	Value
External buzzer / LED	supported
Board mounting pattern	25.5 × 25.5 mm

The **ExpressLRS 2.4 GHz** receiver communicates with the flight controller via the CRSF protocol. In the configuration published by the manufacturer for the Huma20 (CLI files on sub250.com), the receiver is connected to UART2 and the video transmitter to UART4 (MSP + DisplayPort for displaying the OSD in the goggles).

2.5 DJI O4 Air Unit Pro video transmitter and camera

Digital video transmission and video recording are handled by the DJI O4 Air Unit Pro. Data as stated by the manufacturer DJI:

Parameter	Value
Sensor / lens	1/1.3" CMOS; FOV 155°, f/2.8
Video recording	up to 4K (3840 × 2160) at 120 fps, MP4, max. 130 Mb/s
Colour modes	Normal, D-Log M
Stabilisation	RockSteady 3.0+, Gyroflow support
Internal storage	4 GB; microSD up to 512 GB
Video transmission to goggles	1080p at 30/48/50/60/100 fps
Frequency bands	5.170–5.250 GHz; 5.725–5.850 GHz
Transmit power (e.i.r.p., CE)	5.1 GHz: < 23 dBm; 5.8 GHz: < 14 dBm
Compatible goggles	DJI Goggles 3, Goggles N3, Goggles 2, Goggles Integra
Operating temperature	−10 °C to 40 °C

※ The DJI O4 Pro camera uses a new generation of gyroscopes that are more sensitive to vibration. This may affect RockSteady and Gyroflow stabilisation. Keep the propellers in perfect condition.

3. Legal requirements for operation in the Czech Republic and the EU

3.1 The law of the country where you fly applies

Regulations (EU) 2019/947 and 2019/945 apply in all member states of the European Union, but national implementing rules differ from country to country – registration portals, minimum pilot age, geographical zones, mandatory insurance, permitted frequency bands and maximum transmit power. The information in this chapter describes the situation in the Czech Republic. **If you operate the drone in another country, you must comply with the regulations of the country in which you fly.**

3.2 Drone classification and category of operation

- The Huma20 O4 Pro **does not bear a class identification label** C0–C6 under Regulation (EU) 2019/945 and was placed on the market after 1 January 2024.
- The transitional provision of Article 20 of Regulation (EU) 2019/947, which allows older drones without a class label to be flown in subcategories A1 and A3, applies only to drones placed on the market **before 1 January 2024**. It therefore does not apply to this drone.
- A weight below 250 g does not in itself qualify the drone for subcategory A1.
- Reliable ways of operating legally are **flying within a model aircraft association or club holding an authorisation** under Article 16 of Regulation (EU) 2019/947, or **operation in the specific category** on the basis of an authorisation from the Civil Aviation Authority of the Czech Republic (ÚCL).
- Interpretation may vary from case to case. Before your first flight, check the current requirements with the ÚCL (www.caa.gov.cz).

3.3 Operator registration and pilot competency

- The drone is equipped with a camera, i.e. a sensor capable of capturing personal data. **Operator registration is therefore mandatory regardless of weight** (Article 14 of Regulation (EU) 2019/947). In the Czech Republic, operators register on the dron.caa.gov.cz portal.
- The operator registration number must be clearly displayed on the drone.
- The pilot must hold a competency appropriate to the category of operation (A1/A3 online training and examination on the ÚCL portal; in the specific category, as required by the authorisation).
- The minimum age of a remote pilot in the Czech Republic is 16 years.

3.4 Operational limits

- The maximum flight height is 120 m above the ground unless the authorisation specifies otherwise.

- The drone must remain within visual line of sight (VLOS).
- Do not fly over assemblies of people and keep a safe distance from uninvolved persons.
- Respect geographical zones. In the Czech Republic, the official source is the DroneMap map (dronemap.gov.cz).

3.5 Flying with FPV goggles

When flying with FPV goggles, the pilot cannot see the drone directly. The visual line of sight requirement is therefore met by a **UA observer** who stands next to the pilot, watches the drone without optical aids and communicates with the pilot continuously. The pilot remains responsible for the safety of the flight.

3.6 Radio frequencies and transmit power

The drone contains two radio devices: an ExpressLRS 2.4 GHz receiver (with telemetry) and a DJI O4 Air Unit Pro video transmitter. In the Czech Republic, the following conditions of the ČTÚ general authorisations apply:

Band	Limit in the Czech Republic	Device / note
2400–2483.5 MHz	100 mW e.i.r.p.	ELRS receiver (telemetry), radio; VO-R/12
5170–5250 MHz	200 mW e.i.r.p.	DJI O4 Air Unit Pro; VO-R/12. Unmanned aircraft systems must not be operated in the 5150–5170 MHz sub-band.
5725–5850 MHz	25 mW e.i.r.p.	DJI O4 Air Unit Pro; VO-R/10

- Maximum transmit power of the video transmitter according to DJI data for the EU (CE): 5.1 GHz < 23 dBm, 5.8 GHz < 14 dBm e.i.r.p.
- When activated and connected to DJI Assistant 2, the video transmitter automatically switches to the radio mode for the region. **The user is responsible for setting the transmit power of both the radio and the video transmitter.**
- Outside the Czech Republic, the frequencies and limits of the country concerned apply.

3.7 Data protection and insurance

- When filming, respect the privacy of others and data protection rules (GDPR). Do not record people without their consent.
- In the specific category, third-party liability insurance is mandatory in the Czech Republic (§ 54d of Act No. 49/1997 Coll.). In all other cases, we strongly recommend insurance.

4. Preparing for the first flight

4.1 What else you need

- A **radio (transmitter)** with an ExpressLRS 2.4 GHz transmitter module (e.g. running EdgeTX firmware).
- **DJI FPV goggles** compatible with the O4 Air Unit Pro (Goggles 3, Goggles N3, Goggles 2 or Goggles Integra).
- **4S Li-Po batteries** with an XT30 connector – the manufacturer recommends a capacity of 720 mAh – and a suitable charger.
- A microSD card for high-quality video recording.
- A computer with Betaflight Configurator and DJI Assistant 2 (Consumer Drones Series), and a USB-C cable.

4.2 Choosing and connecting the battery

- Use **4S** batteries only. A battery with a higher cell count will damage the drone.
- Always fit a **fully charged** battery before flying: Li-Po 4.20 V/cell (16.8 V), LiHV 4.35 V/cell (17.4 V).
- Secure the battery with the strap so that it cannot shift in flight, and route the lead away from the propellers.
- Connect the XT30 connector observing correct polarity, smoothly and only just before the flight; then keep the drone still until the gyroscope has calibrated.

State	Li-Po 4S	LiHV 4S
Fully charged	16.8 V (4.20 V/cell)	17.4 V (4.35 V/cell)
End flight	14.0 V (3.5 V/cell)	14.0 V (3.5 V/cell)
Storage	15.2 V (3.8 V/cell)	15.2 V (3.8 V/cell)

4.3 Propellers

- The drone is supplied with HQProp 2×2.2×4 propellers fitted; spares are included in the package.
- Each propeller must match the direction of rotation of its motor. When replacing one, fit a propeller of the same type as was on that motor.

4.4 Camera and microSD card

- Remove the protective film from the lens before first use.
- Insert and remove the microSD card only with the battery disconnected.
- According to DJI, recording stops when the motors stop. While the drone is on the ground waiting for take-off, recording does not start by default.

5. Setup

5.1 Connecting to a computer

- Remove the propellers and connect the flight controller to the computer with a USB-C cable.
- Launch Betaflight Configurator and connect. The flight controller reports the firmware target **SUB250REDFOXF722AIO**.
- The drone is configured at the factory. Before changing anything, save a backup of the configuration using the *diff all* command in the *CLI* tab.
- The manufacturer publishes configuration files (CLI) for the Huma20 on sub250.com under *Support Center → CLI Configuration*. For this version, use the ELRS file.

5.2 Activating and pairing the DJI O4 Air Unit Pro

Procedure according to the DJI user manual:

① **Activation** – connect the battery to the drone (the video transmitter must be powered from the flight controller) and connect the video transmitter to the computer via its USB-C port. In **DJI Assistant 2 (Consumer Drones Series)**, log in with your DJI account and activate the device. A non-activated video transmitter has limited output power (≤ 20 mW).

② **Firmware update** – in DJI Assistant 2, update the video transmitter, the goggles and any DJI controller to the latest version, then restart the devices.

③ **Pairing** – power on the goggles and the drone. Briefly press the Link button on the video transmitter (the status LED blinks red), then press the pairing button on the goggles (the goggles beep).

④ Once pairing has succeeded, the video transmitter LED is solid green, the goggles stop beeping and display the camera image.

※ The order of the steps may differ between goggle models – follow the manual for your DJI goggles. Keep the propellers removed while working with the battery connected.

5.3 Binding the ExpressLRS receiver

The receiver and the transmitter module must run ExpressLRS firmware with the same major version number. Binding is possible in two ways:

▶ Binding phrase

Set the same *binding phrase* in both the receiver and the transmitter module (when flashing the firmware in ExpressLRS Configurator or via the WiFi web interface). The devices will then connect automatically when powered on.

▶ Bind mode

① Switch off the radio.

② Put the receiver into bind mode: connect the battery and disconnect it again within 2 seconds, three times in a row, or use the *Bind Receiver* button in the *Receiver* tab of Betaflight Configurator (or the *bind_rx* command in the CLI).

③ The receiver LED blinks twice, pauses briefly and repeats – the receiver is in bind mode.

④ Switch on the radio and select **[Bind]** in the ExpressLRS Lua script.

⑤ A solid LED means the receiver is bound.

Receiver LED	Meaning
solid	connected to the radio
double blink and pause	bind mode
slow blinking (500 ms)	waiting for connection to the radio
triple blink and pause	connected, but the Model Match setting does not match
fast blinking (25 ms)	WiFi mode (update)

According to the ExpressLRS documentation, a receiver without a connection automatically switches to WiFi mode after a set time. Firmware update via WiFi: connect to the *ExpressLRS RX* network (password *expresslrs*) and open http://10.0.0.1/.

5.4 Switches and flight modes

In the configuration published by the manufacturer for the Huma20, the following functions are set up in the *Modes* tab (active in the 1700–2100 µs range):

Channel	Function
AUX1 (channel 5)	**ARM** – Arm / Disarm
AUX2 (channel 6)	**ANGLE** – self-levelling mode; otherwise the drone flies in Acro mode
AUX3 (channel 7)	**BEEPER** – audible alarm for locating the drone

In the *Receiver* tab, check that stick and switch movements correspond to the channels (AETR mapping) and that the channels respond in the correct direction. Set up the switches on the radio according to the table, or change the assignments in the *Modes* tab.

5.5 Motor check

- **With the propellers removed**, connect the battery and connect the drone to the computer.
- In the *Motors* tab, acknowledge the safety warning and spin up each motor in turn at low speed.
- Check that the correct motor spins and that it rotates in the direction shown by Betaflight.

- Use accelerometer calibration (*Setup → Calibrate Accelerometer*) only if the drone drifts by itself in ANGLE mode; the drone must stand on a level surface during calibration.

5.6 Arm, Disarm and failsafe

- **Arm** (motor enable) – throttle at minimum, drone stationary on a level surface, flip the ARM switch. The motors spin up to idle.
- **Disarm** (motor disable) – flip the ARM switch back. Disarm immediately after landing or in the event of a crash.
- If the drone will not Arm, Betaflight shows the reason in the *Setup* tab (e.g. throttle not at minimum, no signal, drone tilted too far).
- **Failsafe** – if the radio signal is lost, the manufacturer's configuration cuts the motors after a short delay (DROP procedure) and the drone falls. Test the failsafe function with the propellers removed by switching off the radio.

5.7 Firmware and further guides

- The firmware of the flight controller, ESC, receiver and video transmitter is supplied pre-configured by the manufacturer. Update only when necessary and always with a configuration backup.
- Flight controller: Betaflight, target SUB250REDFOXF722AIO. ESC: BLHeli_32.
- Receiver: ExpressLRS – when updating, select the regulatory domain corresponding to the country of operation.
- Video transmitter: DJI Assistant 2 (Consumer Drones Series), www.dji.com/o4-air-unit/downloads.

Official documentation: www.expresslrs.org and edgetx.org.

6. Flying

6.1 Pre-flight check

- Make sure you are permitted to fly at the location and that the area is safe and clear of uninvolved persons.
- Fit a **fully charged** battery (4S Li-Po 16.8 V, LiHV 17.4 V) and secure it firmly.
- Check the propellers, propeller guards, frame, screws, antennas and cables. Nothing may reach into the propellers.
- Switch on the radio and goggles first; only then connect the battery to the drone.
- Check the radio link (OSD in the goggles, telemetry) and the function of the ARM switch.
- Check that a microSD card is inserted and has enough space for recording.
- The UA observer is standing next to you and is ready.

6.2 Take-off and basic control

- Place the drone on a level surface, step back to a safe distance and Arm.
- Smoothly increase the throttle and climb to a safe height. Beginner pilots should start in ANGLE mode.
- The drone is powerful and responds very quickly. Fly slowly at first, in an open area; you can learn the controls beforehand on an FPV simulator.

6.3 Monitoring voltage and ending the flight

- Monitor the battery voltage in the goggles OSD. The manufacturer's configuration warns of low voltage at 3.5 V/cell.
- End the flight at **3.5 V/cell (14.0 V)** at the latest. Voltage drops under load and recovers slightly when the load is removed – the resting voltage is what counts.
- After landing, Disarm immediately, disconnect the battery and only then pick up the drone.
- Do not discharge the battery further after the flight; before storage, set it to 3.8 V/cell (15.2 V).

6.4 Locating the drone after a crash

- Disarm immediately after a crash.
- Activate the audible alarm with the BEEPER switch (AUX3). If the radio signal is lost, the alarm activates automatically according to the manufacturer's configuration.
- If the battery is disconnected, the alarm does not work – so start searching as soon as possible.

7. Maintenance and troubleshooting

7.1 After every flight

- Disconnect the battery and let both the drone and the battery cool down.
- Check the propellers, propeller guards, frame and motors. Remove grass, hair and dirt from the motors.
- Check that the screws are tight and that the antennas and camera are secure.
- Clean the drone with a dry brush or compressed air. Do not use water or solvents.

7.2 Replacing propellers and protective parts

- Replace any propeller that is bent, cracked or has a damaged edge – even minor damage increases vibration, which shows up in the footage.
- Fit the propeller with the same direction of rotation as the original one and tighten it firmly.
- Replace damaged frame and propeller guard parts; print files for Huma20 O4 spare parts are available for download on sub250.com.

7.3 Storage

- Store the drone in a dry place at room temperature, out of the reach of children.
- Store batteries disconnected, charged to 3.8 V/cell (15.2 V), in a fireproof container.

7.4 Troubleshooting

Problem	Cause and solution
Drone will not Arm	Throttle not at minimum, drone tilted, no receiver signal, or drone connected to USB. Betaflight shows the reason in the *Setup* tab.
Radio does not connect to the receiver	Different binding phrase or ExpressLRS major firmware version; bind the receiver again (chapter 5.3). A triple LED blink indicates a Model Match mismatch.
No image in the goggles	Video transmitter not paired or not activated; see chapter 5.2 and check the goggles and video transmitter firmware.
Weak or choppy image	Damaged or loose antenna, overheated video transmitter (standing on the ground for a long time), obstacles between the drone and the pilot.
Recording stopped	Overheated video transmitter, full or faulty microSD card, or the motors stopped.
Shaky image, vibration	Damaged or loose propeller, dirt in a motor, loose screws. Replace faulty propellers.
Drone flips over on take-off	Incorrectly fitted propeller (direction of rotation) or wrong motor order or direction; check the *Motors* tab with the propellers removed.
Short flight time	Worn or insufficiently charged battery, capacity too low.

8. Information for the EU and Czech Market

8.1 Importer and responsible person in the EU

The product is placed on the European Union market by the importer stated below, who is at the same time the responsible person within the meaning of Article 16 of Regulation (EU) 2023/988 of the European Parliament and of the Council on general product safety (GPSR).

Importer / responsible person in the EU	Rotorama, s.r.o.
Company ID (IČO)	051 57 692
VAT ID (DIČ)	CZ05157692
Registered office	Okrajová 1351, 674 01 Třebíč, Czech Republic
E-mail	info@rotorama.cz
Phone	+420 252 252 098
Website	www.rotorama.com

8.2 Product conformity

CE

- The product bears the **CE** marking and complies with the requirements of the applicable European Union harmonisation legislation.
- A copy of the **EU Declaration of Conformity** is available from the importer at the address stated above or at the e-mail address info@rotorama.cz.
- **Product identification:** the type designation (Huma20 O4 Pro, 4S ELRS version) is given on the product packaging and on the proof of purchase.

8.3 Disposal of electrical equipment



- The crossed-out wheeled bin symbol on the product, its packaging or in the documentation means that at the end of its service life the product **must not be disposed of together with mixed municipal waste**.
- Hand it over at a take-back point for electrical equipment – at a collection yard, at a take-back point of a collective system, or at the retailer when purchasing a new equivalent product. Take-back is free of charge for the end user.
- The obligations under Act No. 542/2020 Coll., on end-of-life products, are fulfilled by the importer through a collective take-back system.
- Proper disposal helps prevent negative impacts on the environment and human health and contributes to the reuse of secondary raw materials.

Through its contractual partner **ASEKOL a.s.**, the company ensures the take-back of waste electrical equipment from households and the separate collection of waste electrical equipment, batteries and accumulators in accordance with the applicable legislation. The customer is entitled to hand over old electrical equipment or a battery or accumulator at any collection point of the above contractual partner. The addresses of these take-back points are listed at www.asekol.cz, www.ecobat.cz and also https://visoh2.mzp.cz/RegistrMistZO/RegistrMistZOPublic/MapaMistZpetOdberu.

9. Warranty and rights arising from defective performance

The rights and obligations of the contracting parties are governed by Czech law, in particular by Act No. 89/2012 Coll., the Civil Code, and Act No. 634/1992 Coll., on consumer protection.

- The seller is liable to the buyer for the product being free of defects on receipt. If the buyer is a consumer, a defect may be notified **within two years of receipt** of the product (Section 2165 of the Civil Code).
- If a defect appears within **one year** of receipt, the product is deemed to have been defective already at the time of receipt (Section 2161(5) of the Civil Code).
- When purchasing online, a consumer has the right to **withdraw from the contract within 14 days** of receiving the goods without giving a reason (Section 1829 of the Civil Code).
- Claims should be made with the retailer from whom you purchased the product. The importer's contact details are given in Chapter 8.1.
- The competent body for out-of-court settlement of consumer disputes is the **Czech Trade Inspection Authority**, Štěpánská 796/44, 110 00 Prague 1, www.coi.cz.